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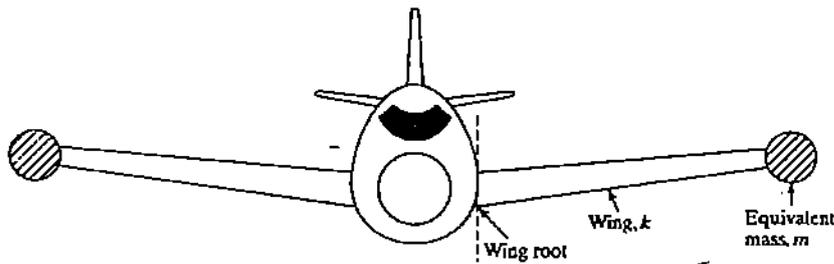
MEN 330  
EXAM 2  
SPRING 2005

100  
Very good

- 1) (15 pts) An airplane, taxiing on a runway, encounters a bump. As a result, the root of the wing is subjected to a displacement that is expressed as

$$y(t) = \begin{cases} Y \left( \frac{t^2}{t_0^2} \right), & 0 \leq t \leq t_0 \\ 0, & t > t_0 \end{cases}$$

Assume that the wing has a stiffness  $k$  and set up the Duhamel integral(s) which would calculate the response of the wing tip mass  $m$  for  $t \in [0, \infty]$ . Set up the integral(s) fully but **do not** attempt to solve the problem.



for  $0 \leq t < t_0$

~~F(t) = K y(t)~~  
 $F(t) = K y(t)$

$$x(t) = \frac{1}{m \omega_d} \int_0^t F(\tau) \sin \omega_d (t - \tau) d\tau$$

with  $\tau = 0 \Rightarrow \omega_d = \omega_n$        $\omega_n = \sqrt{\frac{k}{m}}$

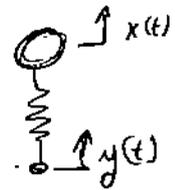
$$\Rightarrow x(t) = \frac{1}{m \omega_n} \int_0^t \frac{k Y}{t_0^2} \tau^2 \sin \omega_n (t - \tau) d\tau \quad \text{for } 0 \leq t < t_0 \quad \checkmark$$

for  $t > t_0$

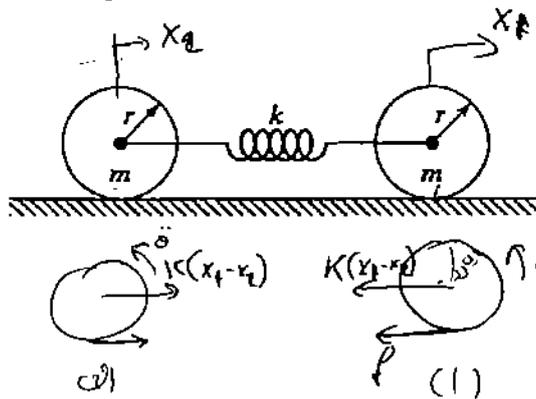
$$x(t) = \frac{1}{m \omega_n} \int_0^{t_0} \frac{k Y}{t_0^2} \tau^2 \sin \omega_n (t - \tau) d\tau + \frac{1}{m \omega_n} \int_{t_0}^t 0 \sin \omega_n (t - \tau) d\tau$$

$$\Rightarrow \text{for } t > t_0 \quad x(t) = \frac{1}{m \omega_n} \int_0^{t_0} \frac{k Y}{t_0^2} \tau^2 \sin \omega_n (t - \tau) d\tau \quad \checkmark$$

15



- 2) (15 pts) Two identical circular cylinders of radius  $r$  and mass  $m$  each, are connected by a spring of stiffness  $k$ . Determine the natural frequencies of oscillation under no-slip conditions.



$$\Sigma M_{(1)} = P r = I \ddot{\theta} \Rightarrow P r = \frac{1}{2} m r^2 \ddot{\theta} \quad \text{but } r \ddot{\theta} = \dot{x}$$

$$\Rightarrow P r = \frac{1}{2} m r \dot{x}_1 \Rightarrow P = \frac{1}{2} m \ddot{x}_1$$

$$\Sigma F = -K(x_1 - x_2) - P = m \ddot{x}_1 = 0$$

$$\Rightarrow m \ddot{x}_1 + \frac{1}{2} m \ddot{x}_1 + K x_2 - K x_1 = 0$$

$$\frac{3}{2} m \ddot{x}_1 + K x_1 - K x_2 = 0 \quad (1)$$

$$\Sigma M_{(2)} = P = -\frac{1}{2} m \ddot{x}_2$$

$$\Sigma F_{(2)} = K(x_1 - x_2) + P - m \ddot{x}_2 = 0$$

$$\Rightarrow m \ddot{x}_2 + \frac{1}{2} m \ddot{x}_2 - K x_1 + K x_2 = 0$$

$$\Rightarrow \frac{3}{2} m \ddot{x}_2 - K x_1 + K x_2 = 0 \quad (2)$$

$$\begin{pmatrix} \frac{3}{2} m & 0 \\ 0 & \frac{3}{2} m \end{pmatrix} \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} + \begin{pmatrix} K & -K \\ -K & K \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

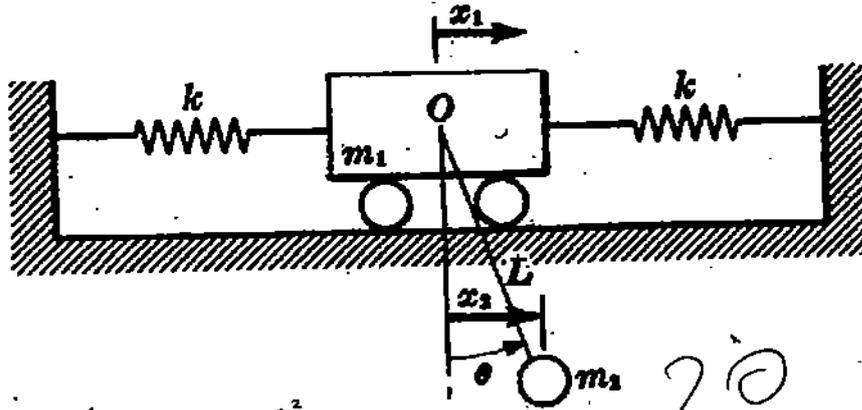
$$\det(-\omega^2 M + K) = 0 \Rightarrow \begin{pmatrix} -\frac{3}{2} m \omega^2 + K & -K \\ -K & -\frac{3}{2} m \omega^2 + K \end{pmatrix} = 0$$

$$\Rightarrow \frac{9}{4} m^2 \omega^4 - \frac{9}{4} m K \omega^2 + K^2 - K^2 = 0$$

$$\Rightarrow \frac{9}{4} m^2 \omega^4 - 3 m K \omega^2 = 0 \Rightarrow \omega^2 \left( \frac{9}{4} m^2 \omega^2 - 3 m K \right) = 0$$

$$\Rightarrow \omega = 0 \quad \omega_1^2 = \frac{3 m K}{9 - 2} \Rightarrow \omega_2 = \sqrt{\frac{4 K}{3 m}}$$

3) (20 pts) Determine the natural frequencies of the system for small oscillations.



FBD 1

$$\Sigma M_O = I_O \ddot{\theta} \quad \text{also } I_O = m_2 L^2$$

$$\Rightarrow -m_2 g L \theta - m_2 L \ddot{x}_1 - m_2 L^2 \ddot{\theta} = 0$$

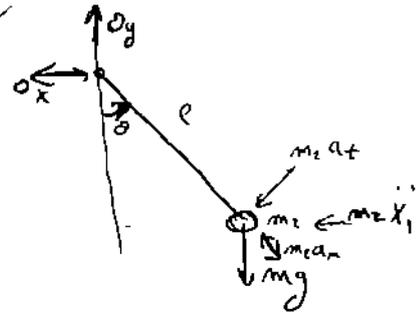
$$\Rightarrow m_2 L^2 \ddot{\theta} + m_2 L \ddot{x}_1 + m_2 g L \theta = 0 \quad \text{--- (1)}$$

$$\Sigma F_x \Rightarrow -O_x - m_2 \ddot{x}_1 - m_2 a_t - m_2 a_n \theta = 0$$

$$\Rightarrow -O_x - m_2 \ddot{x}_1 - m_2 L \ddot{\theta} + m_2 L \dot{\theta}^2 = 0$$

$$\Rightarrow O_x = m_2 L \dot{\theta}^2 - m_2 \ddot{x}_1 - m_2 L \ddot{\theta}$$

$a_n = \frac{v^2}{r} = \frac{L^2 \dot{\theta}^2}{L} = L \dot{\theta}^2$



FBD 2

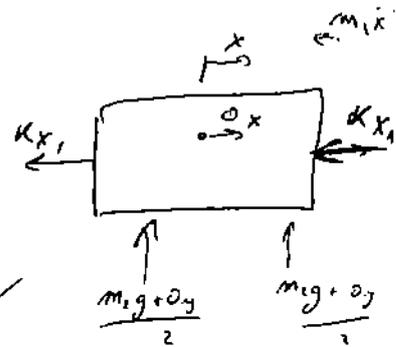
$$\Sigma F_x = O_x - 2Kx_1 - m_1 \ddot{x}_1 = 0$$

can be neglected

$$m_2 L \dot{\theta}^2 - m_2 \ddot{x}_1 - m_2 L \ddot{\theta} - 2Kx_1 - m_1 \ddot{x}_1 = 0$$

$$\Rightarrow m_1 \ddot{x}_1 + m_2 \ddot{x}_1 + m_2 L \ddot{\theta} + 2Kx_1 = 0$$

$$\Rightarrow (m_1 + m_2) \ddot{x}_1 + m_2 L \ddot{\theta} + 2Kx_1 = 0 \quad \text{--- (2)}$$



$$\begin{pmatrix} m_1+m_2 & m_2 L \\ m_2 L & m_2 L^2 \end{pmatrix} \begin{pmatrix} \ddot{x} \\ \ddot{\theta} \end{pmatrix} + \begin{pmatrix} 2K & 0 \\ 0 & m_2 g L \end{pmatrix} \begin{pmatrix} x \\ \theta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$M \qquad \qquad \qquad K \qquad \qquad \qquad x$

~~det M~~

$$\det(-\omega^2 M + K) = 0 \Rightarrow \begin{pmatrix} -(m_1+m_2)\omega^2 + 2K & -m_2 L \omega^2 \\ -m_2 L \omega^2 & -m_2 L^2 \omega^2 + m_2 g L \end{pmatrix} = 0.$$

$$\Rightarrow (m_1+m_2)m_2 L^2 \omega^4 - (m_1+m_2)m_2 g L \omega^2 - 2m_2 L^2 K \omega^2 + 2m_2 g L K - m_2^2 L^2 \omega^4 = 0.$$

Solve for  $\omega$

$$\Rightarrow m_1 m_2 L^2 \omega^4 + m_2^2 L^2 \omega^4 - m_1 m_2 g L \omega^2 - m_2^2 g L \omega^2 - 2m_1 L^2 K \omega^2 + 2m_2 g L K - m_2^2 L^2 \omega^4 = 0$$

~~$$m_1 m_2 L^2 \omega^4 + m_2^2 L^2 \omega^4 - m_1 m_2 g L \omega^2 - m_2^2 g L \omega^2 - 2m_1 L^2 K \omega^2 + 2m_2 g L K - m_2^2 L^2 \omega^4 = 0$$~~

$$m_1 L \omega^4 - m_1 g \omega^2 - m_2 g \omega^2 - 2 L K \omega^2 + 2 g K = 0 \quad \text{--- (3)}$$

$$m_1 L \omega^4 - (m_1 g + m_2 g + 2 L K) \omega^2 + 2 g K = 0.$$

$a \qquad \qquad \qquad b \qquad \qquad \qquad c$

The natural frequencies  $\omega_1$  and  $\omega_2$  are the roots of eq. (3).

$$\Delta = b^2 - 4ac =$$

$$\omega_1 = \frac{b + \sqrt{\Delta}}{2a}$$

$$\omega_2 = \frac{b - \sqrt{\Delta}}{2a}$$